## Amendments to the Claims:

Please cancel claims 12 and 29, amend claims 10 and 13, and add new claims 30-34 as shown in the following listing of claims. This listing of claims will replace all prior versions, and listings, of claims in the application.

- 1 1. (previously presented) A system for measuring a three-dimensional object, 2 said system comprising:
- 3 a base;

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- elongate measuring members operatively connected to said base 4
- such that said elongate measuring members can be displaced with respect to said 5
- base in response to a surface of said three-dimensional object, said elongate 6
- measuring members including displacement information embedded in said
- elongate measuring members along the lengths of said elongate measuring 8
- 9 members; and
- 10 means for determining displaced distances of said elongate
- measuring members due to said surface of said three-dimensional object, said 11
- displaced distances of said elongate measuring members being measurements of 12
- said surface of said three-dimensional object, said determining means being 13
- configured to optically use said displacement information of said elongate 14
- measuring members at displaced locations along the lengths of said elongate 15
- measuring members to determine said displaced distances. 16
- (original) The system of claim 1 wherein said elongate measuring ı 2.
- members are operatively connected to said base such that said elongate measuring 2
- members can be displaced in a direction parallel to central axes of said elongate 3
- measuring members, said central axes corresponding to the lengths of said 4
- 5 elongate measuring members.
- (canceled). 3. 1
- 1 4. (canceled).

- 1 5. (previously presented) The system of claim 1 wherein said determining
- 2 means includes optical sensors that are coupled to said base, said optical sensors
- 3 being configured to optically read said displacement information embedded in
- 4 said clongate measuring members at said displaced locations along the lengths of
- 5 said elongate measuring members.
- 1 6. (original) The system of claim 5 wherein said elongate measuring
- 2 members have reflectivity that varies along the lengths of said elongate measuring
- 3 members, said reflectivity of said elongate measuring members being said
- 4 displacement information embedded in said elongate measuring members.
- 1 7. (previously presented) The system of claim 5 wherein said displacement
- 2 information embedded in said elongate measuring members includes different
- 3 codes along the length of each of said elongate measuring members.
- 1 8. (previously presented) The system of claim 1 wherein said elongate
- 2 measuring members have transmissivity that varies along the lengths of said
- 3 elongate measuring members, and wherein said determining means includes light
- 4 sources and an imaging sensor, said light sources being positioned to project lights
- 5 into said elongate measuring members at said displaced locations along the
- 6 lengths of said elongate measuring members, said imaging sensor being
- 7 positioned to capture an image of light-emitting ends of said elongate measuring
- 8 members.
- 9. (original) The system of claim 8 further comprising a processing unit
- 2 configured to process said image to determine intensities of lights emitted from
- 3 said light-emitting ends of said elongate measuring members, said intensities of
- 4 lights corresponding to said displaced distances of said clongate measuring
- 5 members.

- (original) The system of claim 10 wherein said elongate measuring 11. 1
- members are operatively connected to said base such that said clongate measuring 2
- members can be displaced in a direction parallel to central axes of said elongate 3
- measuring members, said central axes corresponding to the lengths of said 4
- elongate measuring members. 5
- 12. (canceled). 1

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- (currently amended) The system of claim 10 wherein said displacement-13.
- determining mechanism includes optical sensors that are coupled to said base, said 2
- optical sensors being configured to optically read said displacement information 3
- embedded in track displacements of said elongate measuring members at said
- displaced locations along the lengths of said elongate measuring members.

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- l 14. (canceled).
- 1 15. (canceled).
- 1 16. (canceled).
- 17. (canceled).
- 1 18. (canceled).
- 1 19. (previously presented) A method for measuring a three-dimensional
- 2 object, said method comprising:
- engaging a surface of said three-dimensional object with
- 4 displaceable measuring members, including displacing said displaceable
- 5 measuring members in response to said surface of said three-dimensional object,
- 6 said displaceable measuring members including displacement information
- 7 embedded in said displaceable measuring members along the lengths of said
- 8 elongate measuring members; and
- 9 determining displaced distances of said displaceable measuring
- 10 members by optically using said displacement information of said displaceable
- measuring members at displaced locations along the lengths of said displaceable
- 12 measuring members, said displaced distances providing measurements of said
- 13 surface of said three-dimensional object.
- 1 20. (original) The method of claim 19 wherein said displacing of said
- 2 displaceable measuring members includes displacing said displaceable measuring
- 3 members in a direction parallel to central axes of said displaceable measuring
- 4 members, said central axes corresponding to the lengths of said displaceable
- 5 measuring members.
- ı 21. (canceled).
- ı 22. (canceled).

- (previously presented) The method of claim 19 wherein said determining 23. 1
- of said displaced distances includes reading said displacement information 2
- embedded in said displaceable measuring members at said displaced locations 3
- along the lengths of said displaceable measuring members.
- (previously presented) The method of claim 23 wherein said reading of 24. 1
- said displacement information includes measuring light reflected off said 2
- displaced locations along the lengths of said displaceable measuring members, 3
- said displaceable measuring members having reflectivity that varies along the 4
- lengths of said displaceable measuring members. 5
- (previously presented) The method of claim 23 wherein said reading of 25. 1
- said displacement information includes reading codes on said displaceable 2
- measuring members at said displaced locations along the lengths of said 3
- displaceable measuring members, each of said displaceable measuring members 4
- having different codes along its length. 5
- (previously presented) The method of claim 19 wherein said determining 26. 1
- of said displaced distances includes projecting lights into said displaceable 2
- measuring members at said displaced locations along the lengths of said 3
- displaceable measuring members and capturing an image of light-emitting ends of 4
- said displaceable measuring members, said displaceable measuring members 5
- having transmissivity that varies along the lengths of said displaceable measuring 6
- 7 members.
- (original) The method of claim 26 further comprising processing said 27. 1
- image to determine intensities of lights emitted from said light-emitting ends of 2
- said displaceable measuring members, said intensities of lights corresponding to 3
- said displaced distances of said elongate measuring members.
- (previously presented) The system of claim 7 wherein said different codes 28. 1
- along the length of each of said elongate measuring members include visual 2
- binary patterns of high and low reflective regions. 3

- 1 29. (canceled).
- 1 30. (new) The system of claim 13 wherein said elongate measuring members
- 2 have reflectivity that varies along the lengths of said elongate measuring
- 3 members, said reflectivity of said elongate measuring members being said
- 4 displacement information embedded in said elongate measuring members.
- 1 31. (new) The system of claim 13 wherein said displacement information
- 2 embedded in said elongate measuring members includes different codes along the
- 3 length of each of said elongate measuring members.
- 1 32. (new) The system of claim 31 wherein said different codes along the
- 2 length of each of said elongate measuring members include visual binary patterns
- 3 of high and low reflective regions.
- 1 33. (new) The system of claim 10 wherein said elongate measuring members
- 2 have transmissivity that varies along the lengths of said elongate measuring
- 3 members, and wherein said displacement-determining mechanism includes light
- sources and an imaging sensor, said light sources being positioned to project lights
- 5 into said elongate measuring members at said displaced locations along the
- 6 lengths of said elongate measuring members, said imaging sensor being
- 7 positioned to capture an image of light-emitting ends of said elongate measuring
- 8 members.
- 1 34. (new) The system of claim 33 further comprising a processing unit
- 2 configured to process said image to determine intensities of lights emitted from
- 3 said light-emitting ends of said elongate measuring members, said intensities of
- 4 lights corresponding to said displaced distances of said elongate measuring
- 5 members.